# MATH 7339 - Machine Learning and Statistical Learning Theory 2 

## Section ARMA

1. AR, MA, ARMA
2. Stationarity, causality and invertibility
3. linear process representation of ARMA
4. Autocovariance of an ARMA process
5. Homogeneous linear difference equations

## $\square$ AR(p): Autoregressive Models of order p.

A class of models closely related to the random walk are the autoregressive models (AR). An autoregressive model is defined so that the current location is a linear combination of previous locations plus a random term (Gaussian white noise).

The $\mathbf{A R}(\mathbf{p})$ model is

$$
X_{t}=\phi_{1} X_{t-1}+\cdots+\phi_{p} X_{t-p}+W_{t}
$$

where $W_{t} \sim W N\left(0, \sigma^{2}\right)$
Let $B$ be the backshift operator, $B X_{t}:=X_{t-1}$. The above two $\operatorname{AR}(\mathrm{p})$ descriptions can be written as

$$
\left(1-\phi_{1} B-\cdots-\phi_{p} B^{p}\right) X_{t}=W_{t} \quad \text { or } \phi(B) X_{t}=W_{t}
$$

Question: Under what condition(s) is the random walk a special case of an AR model?

## $\square$ MA(q): Moving Average Models or order q

One way to think about Moving Average models is to take a sliding window and take a weighted average of a white noise process for everything in the window. So, start with a white noise process, $\left\{W_{t}\right\}$. Then a moving average of order $q$ is of the following form

$$
X_{t}=W_{t}+\theta_{1} W_{t-1}+\cdots+\theta_{q} W_{t-q}
$$

where $W_{t} \sim W N\left(0, \sigma^{2}\right)$

Use backshift operator

$$
X_{t}=\left(1+\theta_{1} B+\cdots \theta_{q} B^{q}\right) W_{t} \quad \text { or } X_{t}=\theta(B) W_{t}
$$

## $\square$ ARMA(p,q): Autoregressive moving average models

An ARMA $(\mathbf{p}, \mathbf{q})$ process $\left\{X_{t}\right\}$ is a stationary process that satisfies

$$
X_{t}-\phi_{1} X_{t-1}-\cdots-\phi_{p} X_{t-p}=W_{t}+\theta_{1} W_{t-1}+\cdots+\theta_{q} W_{t-q}
$$

where $W_{t} \sim W N\left(0, \sigma^{2}\right)$

$$
\text { or } \phi(B) X_{t}=\theta(B) W_{t}
$$

ARMA processes can accurately approximate many stationary processes.

Theorem: For any stationary process with autocovariance $\gamma$ and any $k>0$, there is an ARMA process $\left\{X_{t}\right\}$ for which

$$
\gamma_{X}(h)=\gamma(h) \quad \text { for } h=0,1, \ldots, k
$$

$\operatorname{AR}(p)=\operatorname{ARMA}(p, 0)$.
$\operatorname{MA}(q)=\operatorname{ARMA}(0, q)$.
Usually, we insist that $\phi_{p}, \theta_{q} \neq 0$ and that the polynomials

$$
\begin{aligned}
& \phi(z)=1-\phi_{1} z-\cdots-\phi_{p} z^{p} \\
& \theta(z)=1+\theta_{1} z+\cdots+\theta_{q} z^{q}
\end{aligned}
$$

have no common factors. This implies it is not a lower order ARMA model.

## Example of parameter redundancy

A white noise process $X_{t}=W_{t}$

So

$$
X_{t}-X_{t-1}+0.5 X_{t-2}=W_{t}-W_{t-1}+0.5 W_{t-2}
$$

So,

$$
\left(1-B+0.5 B^{2}\right) X_{t}=\left(1-B+0.5 B^{2}\right) W_{t}
$$

This is in the form of an $\operatorname{ARMA}(2,2)$ process. But it is white noise.

There are a few issues with ARMA models:

- Parameter redundancy in models.
- AR models that depend on the future.
- MA models that are not unique..

To overcome these issues, we require some restrictions on the model parameters

## AR(1) in terms of the back-shift operator

Assume that $X_{t}$ is stationary solution to

$$
X_{t}=\phi X_{t-1}+W_{t}
$$

If $|\phi|<1$, then

$$
X_{t}=\sum_{j=0}^{\infty} \phi^{j} W_{t-j}
$$

Let $B$ be the backshift operator, $B X_{t}:=X_{t-1}$. The above two $\operatorname{AR}(1)$ descriptions can be written as

$$
(1-\phi B) X_{t}=W_{t} \quad \text { and } \quad X_{t}=\sum_{j=0}^{\infty} \phi^{j} B^{j} W_{t}=\pi(B) W_{t}
$$

Denote

$$
\phi(B)=1-\phi B \quad \text { and } \quad \pi(B)=\sum_{j=0}^{\infty} \phi^{j} B^{j}
$$

So, $\pi(B)=\phi(B)^{-1}$ as in the Taylor expansion of $\frac{1}{1-\phi B}$

A linear process $\left\{X_{t}\right\}$ is causal (strictly, a causal function of $\left\{W_{t}\right\}$ ) if there is a

$$
\psi(B)=\psi_{0}+\psi_{1} B+\cdots+\psi_{t} B^{2}+\cdots
$$

with

$$
\sum_{j=0}^{\infty}\left|\psi_{j}\right|<\infty \quad \text { and } \quad X_{t}=\psi(B) W_{t}
$$

## Example.

- $\operatorname{AR}(1)$ is causal if $|\phi|<1$.
- $\mathrm{MA}(\mathrm{q})$ is causal.

A linear process $\left\{X_{t}\right\}$ is Invertible (strictly, a invertible function of $\left\{W_{t}\right\}$ ) if there is a

$$
\pi(B)=\pi_{0}+\pi_{1} B+\cdots+\pi_{t} B+\cdots
$$

with

$$
\sum_{j=0}^{\infty}\left|\pi_{j}\right|<\infty \quad \text { and } \quad W_{t}=\pi(B) X_{t}
$$

- Causality and Invertibility are properties of $\left\{X_{t}\right\}$ and $\left\{W_{t}\right\}$

Example.

- $\operatorname{AR}(1)$ is causal if $|\phi|<1$.

Consider the MA(1) process defined by

$$
X_{t}=W_{t}+\theta W_{t-1}=(1+\theta B) W_{t}
$$

So, if $|\theta|<1$, we have the Tayler series expansion

$$
W_{t}=\frac{1}{1+\theta B} X_{t}=\sum_{j=0}^{\infty}(-\theta)^{j} B^{j} X_{t}
$$

So, MA(1) is invertible if $|\theta|<1$.
$\square$ AR(p): Stationarity and causality

Theorem: A (unique) stationary solution to $\phi(B) X_{t}=W_{t}$ exists iff

$$
\phi(z)=1-\phi_{1} z-\cdots-\phi_{p} z^{p}=0 \text { implies }|z| \neq 1
$$

This $A R(p)$ process is causal iff

$$
\phi(z)=1-\phi_{1} z-\cdots-\phi_{p} z^{p}=0 \text { implies }|z|>1
$$

$\square$ Calculating $\psi$ for an $\operatorname{AR}(p)$ : matching coefficients.

AR(p) model:

$$
X_{t}=\phi_{1} X_{t-1}+\cdots+\phi_{p} X_{t-p}+W_{t}
$$

Equivalently, $\phi(B) X_{t}=W_{t}$, where

$$
\phi(B)=1-\phi_{1} B-\cdots-\phi_{p} B^{p}
$$

Let us solve $\psi(B)$ such that

$$
X_{t}=\psi(B) W_{t}
$$

So,

$$
\psi(B) \phi(B)=1
$$

Equivalently,

$$
\left(\psi_{0}+\psi_{1} B+\cdots+\psi_{t} B^{t}+\cdots\right)\left(1-\phi_{1} B-\cdots-\phi_{p} B^{p}\right)=1
$$

Equivalently, $\quad \psi_{0}=1$

$$
\begin{aligned}
& \psi_{1}-\phi_{1} \psi_{0}=0 \\
& \psi_{2}-\phi_{1} \psi_{1}-\phi_{2} \psi_{0}=0 \\
& \cdots \cdots \\
& \psi_{k}-\sum_{s=1}^{p} \phi_{s} \psi_{k-s}=0 \quad \text { for } k>0
\end{aligned}
$$

Equivalently, $\quad \psi_{j}=0$ for $j<0$

$$
\begin{aligned}
& \psi_{0}=1 \\
& \phi(B) \psi_{j}=0
\end{aligned}
$$

We can solve these linear difference equations in several ways:

- numerically, or
- by guessing the form of a solution and using an inductive proof, or
- by using the theory of linear difference equations.


## Calculating $\boldsymbol{\psi}$ for an ARMA(p,q): matching coefficients

Example: $\phi(B) X_{t}=\theta(B) W_{t}$

$$
\left(1+0.25 B^{2}\right) X_{t}=(1+0.2 B) W_{t}
$$

Let us solve $\psi(B)$ such that

$$
X_{t}=\psi(B) W_{t}
$$

So,

$$
(1+0.2 B)=\left(1+0.25 B^{2}\right)\left(\psi_{0}+\psi_{1} B+\cdots+\psi_{t} B^{t}+\cdots\right)
$$

Compare the same degree of $B$, we have the first order differential equation of $\psi_{i}$ as $\theta_{j}=\phi(B) \psi_{j}$ with $\theta_{0}=1$ and $\theta_{j}=0$ otherwise.

We can use the $\theta_{j}$ to give the initial conditions and solve it using the theory of homogeneous difference equations.

$$
\psi_{j}=\left(1, \frac{1}{5},-\frac{1}{4},-\frac{1}{20}, \frac{1}{16}, \frac{1}{80},-\frac{1}{64},-\frac{1}{320}, \ldots\right)
$$

The method is the same for the general case.

## ARMA(p,q):Stationarity, causality, and invertibility

Theorem: If $\phi$ and $\theta$ have no common factors, the $\operatorname{ARMA}(p, q)$ process is the (unique) solution to

$$
\phi(B) X_{t}=\theta(B) W_{t}
$$

- This ARMA process is stationary iff the roots of $\phi(z)$ avoid the unit circle, i.e.,

$$
\phi(z)=1-\phi_{1} z-\cdots-\phi_{p} z^{p}=0 \text { implies }|z| \neq 1
$$

- This ARMA process is casual iff the roots of $\phi(z)$ outside the unit circle, i.e.,

$$
\phi(z)=1-\phi_{1} z-\cdots-\phi_{p} z^{p}=0 \text { implies }|z|>1
$$

- This ARMA process is invertible iff the roots of $\theta(z)$ outside the unit circle, i.e.,

$$
\theta(z)=1+\theta_{1} z+\cdots+\theta_{q} z^{q}=0 \text { implies }|z|>1
$$

## Example: (ARMA(1,1))

$$
(1-1.5 B) X_{t}=(1+0.2 B) W_{t}
$$

1. $\phi$ and $\theta$ have no common factors, and $\phi$ 's root is at $\frac{2}{3}$, which is not on the unit circle, so $\left\{X_{t}\right\}$ is an $\operatorname{ARMA}(1,1)$ process.
2. $\phi$ 's root (at $2 / 3$ ) is inside the unit circle, so $\left\{X_{t}\right\}$ is not causal.
3. $\theta$ 's root is at -5 , which is outside the unit circle, $\left\{X_{t}\right\}$ is invertible.

## Example: (ARMA(2,1))

$$
(1+0.25 B) X_{t}=(1+2 B) W_{t}
$$

1. $\phi$ and $\theta$ have no common factors, and $\phi$ 's root is at $\pm 2 i$, which is not on the unit circle, so $\left\{X_{t}\right\}$ is an $\operatorname{ARMA}(2,1)$ process.
2. $\phi$ 's root (at $\pm 2 i$ ) is outside the unit circle, so $\left\{X_{t}\right\}$ is causal.
3. $\theta$ 's root is at $-1 / 2$, which is inside the unit circle, $\left\{X_{t}\right\}$ is not invertible.
$\square$ Autocovariance functions of linear processes

Suppose the mean of $X_{t}$ is zero. Consider a linear process:

$$
X_{t}=\psi(B) W_{t}
$$

where $\psi(B)=\psi_{0}+\psi_{1} B+\cdots+\psi_{n} B^{n}+\cdots$, and $W_{t}=W N\left(0, \sigma^{2}\right)$

$$
\begin{aligned}
\gamma(h) & =E\left(X_{t} X_{t+h}\right) \\
& =E\left[\left(\psi_{0} W_{t}+\psi_{1} W_{t-1}+\cdots+\psi_{n} W_{t-n}+\cdots\right)\left(\psi_{0} W_{t+h}+\psi_{1} W_{t+h-1}+\cdots\right)\right] \\
& =\sigma^{2}\left(\psi_{0} \psi_{h}+\psi_{1} \psi_{h+1}+\psi_{2} \psi_{h+2}+\cdots\right) \\
& =\sigma^{2} \sum_{j=0}^{\infty} \psi_{j} \psi_{j+h} \quad \text { for } h \geq 0
\end{aligned}
$$

Example: MA(q) process

$$
X_{t}=W_{t}+\theta_{1} W_{t-1}+\cdots+\theta_{q} W_{t-q}=\theta(B) W_{t}
$$

The autocovariance:

$$
\gamma(h)=\left\{\begin{array}{cc}
\sigma^{2} \sum_{j=0}^{q-h} \theta_{j} \theta_{j+h} & \text { for } h \leq q \\
0 & \text { for } h>q
\end{array}\right.
$$

The autocorrelation function (ACF) of an $\mathrm{MA}(\mathrm{q})$ model is

$$
\rho(h)=\frac{\gamma(h)}{\gamma(0)}=\left\{\begin{array}{cl}
\frac{\sum_{j=0}^{q-h} \theta_{j} \theta_{j+h}}{1+\theta_{1}^{2}+\cdots+\theta_{q}^{2}} & \text { for } h \leq q \\
0 & \text { for } h>q
\end{array}\right.
$$

The ACF will be zero for lags greater than $q$. Thus, the ACF provides information about the order of the dependence for a MA model.

## Autocovariance functions ARMA(p,q) process

$$
\phi(B) X_{t}=\theta(B) W_{t}
$$

Method 1. Write causal ARMA as $X_{t}=\psi(B) W_{t}$, then use the above result for $\gamma(h)$.

Method 2.

$$
\phi(B) X_{t}=\theta(B) W_{t}
$$

$$
X_{t}-\phi_{1} X_{t-1}-\cdots-\phi_{p} X_{t-p}=W_{t}+\theta_{1} W_{t-1}+\cdots+\theta_{q} W_{t-q}
$$

So
$E\left[\left(X_{t}-\phi_{1} X_{t-1}-\cdots-\phi_{p} X_{t-p}\right) X_{t-h}\right]=E\left[\left(W_{t}+\theta_{1} W_{t-1}+\cdots+\theta_{q} W_{t-q}\right) X_{t-h}\right]$

So,

$$
\gamma(h)-\phi_{1} \gamma(h-1)-\cdots-\phi_{p} \gamma(h-p)=\sigma^{2} \sum_{j=0}^{q-h} \theta_{h+j} \psi_{j}
$$

This is a linear difference equation.
$\square$ Homogeneous linear difference equations.

Homogeneous linear difference equations of order $k$ :

$$
a_{0} x_{t}+a_{1} x_{t-1}+\cdots+a_{k} x_{t-k}=0
$$

Equivalently,

$$
\left(a_{0}+a_{1} B+\cdots+a_{k} B^{k}\right) x_{t}=0 \quad \text { or } a(B) x^{t}=0
$$

auxiliary equation:

$$
\begin{gathered}
a_{0}+a_{1} z+\cdots+a_{k} z^{k}=0 \\
\left(z-z_{1}\right)\left(z-z_{2}\right) \cdots\left(z-z_{k}\right)=0
\end{gathered}
$$

The roots of this characteristic polynomial are $z_{i} \in \mathbb{C}$.

$$
\left(B-z_{1}\right)\left(B-z_{2}\right) \cdots\left(B-z_{k}\right) x_{t}=0
$$

So, $\quad\left(B-z_{1}\right) x_{t}=0$

Three cases:

1. The $z_{i}$ are real and distinct.
2. The $z_{i}$ are complex and distinct.
3. Some $z_{i}$ are repeated.

## 1. The $z_{i}$ are real and distinct.

$$
x_{t}=c_{1} z_{1}^{-t}+c_{2} z_{2}^{-t}+\cdots+c_{k} z_{k}^{-t}
$$

Example:

$$
\begin{aligned}
z_{1} & =1.2, z_{2}=-1.3 \\
x_{t} & =c_{1} z_{1}^{-t}+c_{2} z_{2}^{-t}
\end{aligned}
$$


2. The $z_{i}$ are complex and distinct.

$$
x_{t}=c_{1} z_{1}^{-t}+c_{2} z_{2}^{-t}+\cdots+c_{k} z_{k}^{-t}
$$

Suppose $z_{1}$, then there is a complex conjugate root $z_{j}=\overline{z_{1}}$

For example,

$$
x_{t}=c_{1} z_{1}^{-t}+\bar{c}_{1} \bar{z}_{1}^{-t}=2 r\left|z_{1}\right|^{-t} \cos (\omega t-\alpha)
$$

Here $z_{1}=\left|z_{1}\right| e^{i \omega}$ and $c_{1}=r e^{i \alpha}$

Examples: $\quad x_{t}=c_{1} z_{1}^{-t}+\bar{c}_{1} \bar{z}_{1}^{-t}$

$$
z_{1}=1+0.1 i, z_{2}=1-0.1 i
$$

$$
z_{1}=1.2+i, z_{2}=1.2-i
$$



3. Some $z_{i}$ are repeated.

$$
\left(B-z_{1}\right)^{m} x_{t}=0
$$

Check $\left(c_{1}+c_{2} t+\cdots+c_{m-1} t^{m-1}\right) z_{1}^{-t}$ is a solution

Example $z_{1}=z_{2}=1.5$.

$$
\left(c_{1}+c_{2} t\right) z_{1}^{-t}
$$



Find Autocovariance functions of ARMA processes

$$
\begin{gathered}
\left(1+0.25 B^{2}\right) X_{t}=(1+0.2 B) W_{t} \quad \Leftrightarrow \quad X_{t}=\psi(B) W_{t} \\
\psi_{j}=\left(1, \frac{1}{5},-\frac{1}{4},-\frac{1}{20}, \frac{1}{16}, \frac{1}{80},-\frac{1}{64},-\frac{1}{320}, \ldots\right) . \\
\gamma(h)-\phi_{1} \gamma(h-1)-\phi_{2} \gamma(h-2)=\sigma_{w}^{2} \sum_{j=0}^{q-h} \theta_{h+j} \psi_{j} \\
\Leftrightarrow \gamma(h)+0.25 \gamma(h-2)=\left\{\begin{array}{cl}
\sigma_{w}^{2}\left(\psi_{0}+0.2 \psi_{1}\right) & \text { if } h=0, \\
0.2 \sigma_{w}^{2} \psi_{0} & \text { if } h=1, \\
0 & \text { otherwise. }
\end{array}\right.
\end{gathered}
$$

We have the homogeneous linear difference equation

$$
\gamma(h)+0.25 \gamma(h-2)=0
$$

for $h \geq 2$, with initial conditions

$$
\begin{aligned}
\gamma(0)+0.25 \gamma(-2) & =\sigma_{w}^{2}(1+1 / 25) \\
\gamma(1)+0.25 \gamma(-1) & =\sigma_{w}^{2} / 5
\end{aligned}
$$

Homogeneous lin. diff. eqn:

$$
\gamma(h)+0.25 \gamma(h-2)=0
$$

The characteristic polynomial is

$$
1+0.25 z^{2}=\frac{1}{4}\left(4+z^{2}\right)=\frac{1}{4}(z-2 i)(z+2 i)
$$

which has roots at $z_{1}=2 e^{i \pi / 2}, \overline{z_{1}}=2 e^{-i \pi / 2}$.
The solution is of the form

$$
\gamma(h)=c z_{1}^{-h}+\bar{c} \bar{z}_{1}^{-h}
$$

$z_{1}=2 e^{i \pi / 2}, \overline{z_{1}}=2 e^{-i \pi / 2}, c=|c| e^{i \theta}$.
We have

$$
\begin{aligned}
\gamma(h) & =c z_{1}^{-h}+\bar{c} \bar{z}_{1}^{-h} \\
& =2^{-h}\left(|c| e^{i(\theta-h \pi / 2)}+|c| e^{i(-\theta+h \pi / 2)}\right) \\
& =c_{1} 2^{-h} \cos \left(\frac{h \pi}{2}-\theta\right)
\end{aligned}
$$

And we determine $c_{1}, \theta$ from the initial conditions

$$
\begin{aligned}
\gamma(0)+0.25 \gamma(-2) & =\sigma_{w}^{2}(1+1 / 25) \\
\gamma(1)+0.25 \gamma(-1) & =\sigma_{w}^{2} / 5
\end{aligned}
$$

We determine $c_{1}, \theta$ from the initial conditions:


## Notations:

One way to remove linear connections is through linear regression.
Let $\hat{x}_{t+h}$ denote the regression of $x_{t+h}$ on $\left\{x_{t+h-1}, x_{t+h-2}, \ldots, x_{t+1}\right\}$

$$
\hat{x}_{t+h}=\beta_{1} x_{t+h-1}+\beta_{2} x_{t+h-2}+\cdots+\beta_{h-1} x_{t+1}
$$

Here we do not include the intercept assuming the mean of $x_{t}$ is zero. Otherwise, replace $x_{t}$ with $x_{t}-\mu_{x}$.

Let $\hat{x}_{t}$ denote the regression of $x_{t}$ on $\left\{x_{t+1}, x_{t+2}, \ldots, x_{t+h-1}\right\}$

$$
\hat{x}_{t}=\beta_{1} x_{t+1}+\beta_{2} x_{t+2}+\cdots+\beta_{h-1} x_{t+h-1}
$$

Use OLS to estimate the parameters.

$$
X_{t}, X_{t+1}, X_{t+2}, \ldots, X_{t+h-1}, X_{t+h}
$$

## > partial autocorrelation function (PACF)

ACF provides considerable information for MA(q). But for AR(p) and ARMA, ACF tells us little information. We will pursuing a similar function like ACF next.

The Partial AutoCorrelation Function (PACF) of a stationary time series $\left\{X_{t}\right\}$ is

$$
\begin{aligned}
& \phi_{11}=\operatorname{Coor}\left(X_{t+1}, X_{t}\right)=\rho(1) \\
& \phi_{h h}=\operatorname{Coor}\left(X_{t+h}-\hat{X}_{t+h}, X_{t}-\hat{X}_{t}\right) \text { for } h=2,3,4, \ldots
\end{aligned}
$$

This $\phi_{h h}$ is the correlation between $X_{0}$ and $X_{h}$, which removes the linear effects of $X_{1}, \ldots, X_{h-1}$

$$
\ldots, X_{-1}, X_{0}, X_{1}, X_{2}, \ldots, X_{h-1}, X_{h}, X_{h+1}, \ldots
$$

## Autocorrelation Function (ACF) of $\operatorname{AR}(1)$

AR(1) model:

$$
\begin{aligned}
& X_{t}=\phi_{1} X_{t-1}+W_{t} \\
& \gamma(1)=\operatorname{Cov}\left(X_{0}, X_{1}\right)=\phi_{1} \gamma(0) \\
& \gamma(2)=\operatorname{Cov}\left(X_{0}, X_{2}\right) \\
&=\operatorname{Cov}\left(X_{0}, \phi_{1} X_{1}+W_{2}\right) \\
&=\operatorname{Cov}\left(X_{0}, \phi_{1}^{2} X_{0}+\phi_{1} W_{1}+W_{2}\right) \\
&=\phi_{1}^{2} \gamma(0)
\end{aligned}
$$

Clearly, $X_{0}$ and $X_{2}$ are correlated through $X_{1}$.
In the PACF, we remove this dependence by considering the covariance of the prediction errors of $X_{2}^{1}$ and $X_{0}^{1}$

## Partial Autocorrelation Function: AR(1)

Calculate the PACF of a causal $\operatorname{AR}(1)$ model: $X_{t}=\phi X_{t-1}+W_{t}$, with $|\phi|<1$

$$
\phi_{11}=\operatorname{corr}\left(X_{1}, X_{0}\right)=\rho(1)=\phi
$$

Suppose regression $\hat{X}_{t+2}=\beta X_{t+1}$
We choose $\beta$ to minimize

$$
E\left(\left(X_{t+2}-\beta X_{t+1}\right)^{2}\right)=\gamma_{X}(0)-2 \beta \gamma_{X}(1)+\beta^{2} \gamma_{X}(0)
$$

So, $\beta=\phi$. Similarly for the regression $\hat{X}_{t}=\alpha X_{t+1}$

Then

$$
\phi_{22}=\operatorname{Cov}\left(X_{t+2}-\hat{X}_{t+2}, X_{t}-\hat{X}_{t}\right)=0
$$

## Partial Autocorrelation Function: AR(p)

In general, for a causal $\mathbf{A R ( p )}$ model

$$
X_{h}=\phi_{1} X_{h-1}+\cdots+\phi_{p} X_{h-p}+W_{h}
$$

The regression of $X_{h}$ on $X_{h-1}, \ldots, X_{1}$ is

$$
\hat{X}_{h}=\phi_{1} X_{h-1}+\cdots+\phi_{p} X_{h-p}
$$

Thus, when $h>p$, by causality,

$$
\phi_{h h}=\operatorname{Coor}\left(X_{h}-\hat{X}_{h}, X_{0}-\hat{X}_{0}\right)=\left\{\begin{array}{lc}
\phi_{h} & \text { if } 1 \leq h \leq p \\
0 & \text { otherwise }
\end{array}\right.
$$

## ACF and PACF of AR(1)



PACF


## ACF and PACF of Causal AR(2)

AR(2)



## PACF of an invertible MA(q)

$$
\begin{gathered}
X_{t}=W_{t}+\theta_{1} W_{t-1}+\cdots+\theta_{q} W_{t-q}=\theta(B) W_{t} \\
X_{t}=-\sum_{i=1}^{\infty} \pi_{i} X_{t-i}+W_{t} \\
\hat{X}_{n+1}=P\left(X_{n+1} \mid X_{1}, \ldots, X_{n}\right) \\
=P\left(-\sum_{i=1}^{\infty} \pi_{i} X_{n+1-i}+W_{n+1} \mid X_{1}, \ldots, X_{n}\right) \\
=-\sum_{i=1}^{\infty} \pi_{i} P\left(X_{n+1-i} \mid X_{1}, \ldots, X_{n}\right) \\
=-\sum_{i=1}^{n} \pi_{i} X_{n+1-i}-\sum_{i=n+1}^{\infty} \pi_{i} P\left(X_{n+1-i} \mid X_{1}, \ldots, X_{n}\right)
\end{gathered}
$$

In general, $\phi_{h h} \neq 0$

## ACF and PACF of MA(1)



ACF


PACF

## ACF and PACF of Causal MA(2)




## ACF and PACF of Causal ARMA(2,2)

ARMA(2,2)



## Sample PACF

For a realization $x_{1}, \ldots, x_{n}$ of a time series, the sample PACF is defined by

$$
\begin{aligned}
& \hat{\phi}_{00}=1 \\
& \hat{\phi}_{h h}=\text { last component of } \hat{\phi}_{h}
\end{aligned}
$$

where $\hat{\phi}_{h}=\hat{\Gamma}_{h}^{-1} \hat{\gamma}_{h}$

## Summary

- The ACF of MA(q) model cuts off after lag q. The PACF of an AR(p) model cuts off after lag $p$.
- Identification of an MA(q) model is best done with ACF; identification of an $A R(p)$ model is best done with PACF.
- The PACF between $x_{t}$ and $x_{t-h}$ is the correlation between $x_{t}-\hat{x}_{t}$ and $x_{t-h}-\hat{\mathrm{x}}_{\mathrm{t}-\mathrm{h}}$. Think of it as taking the correlation between the residuals from two regression models. The dependence on all intermediate variables is removed.


## ACF and PACF of Causal AR and Invertible MA

|  | $\mathbf{A R}(\mathbf{p})$ | MA(q) | ARMA(p,q) |
| :---: | :---: | :---: | :---: |
|  |  |  |  |
| ACF | Decay | 0 after lag $q$ | Decay |
| PACF | 0 after lag $p$ | Decay | Decay |

Fish Population Example. This time series contains data on fish population in the central Pacific Ocean. The numbers represent the number of new fish in the years 1950-1987.

Question: Based on the ACF and PACF plots, what process do you think is most likely to describe this time series?

Recruitment Series



- "Time Series Analysis and Its Applications", 4th ed. 2017, by Shumway and Stoffer.

Sections 3.1-3.3

Select ARIMA Model for Time Series:
https://www.mathworks.com/help/econ/box-jenkins-model-selection.html

