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### Theorem.

Let  $A$  be an  $n \times n$  matrix. A scalar  $\lambda$  is an eigenvalue for  $A$  if and only if the matrix equation

$$(A - \lambda I_n)\vec{x} = \vec{0}$$

has a *nontrivial* solution  $\vec{x}$ .

Said differently,  $\lambda$  is an eigenvalue for  $A$  if and only if

$$\text{Nul}(A - \lambda I_n) \neq \{\vec{0}\}.$$

### Definition.

Let  $A$  be an  $n \times n$  matrix and  $\lambda$  be a eigenvalue of  $A$ . The set of all eigenvectors of  $A$  corresponding to  $\lambda$  together with the zero vector, is called the **eigenspace** of  $A$  corresponding to  $\lambda$ , and it equals the subspace

$$\text{Nul}(A - \lambda I_n).$$

The dimension of  $\text{Nul}(A - \lambda I_n)$  is called the **geometric multiplicity** of  $\lambda$ .

$$1 \leq \text{Geometric multiplicity of } \lambda \leq \text{Algebraic multiplicity of } \lambda \leq n.$$

**Example 1.** Let  $T$  be the projection transformation onto a line  $L = \text{Span}\left\{\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}\right\} \mathbb{R}^3$ . Explain the geometric meaning of the eigenvalues and eigenspaces.

From §7.1,

$$D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad P = \begin{bmatrix} 1 & 2 & 3 \\ 2 & -1 & 0 \\ 3 & 0 & -1 \end{bmatrix}$$

For  $\lambda = 1$  the eigenspace  $E_{\lambda=1} = L$ .

For  $\lambda = 0$  the eigenspace  $E_{\lambda=0} = L^\perp$ .

**Example 2.** Find all eigenvalues and the corresponding eigenspaces of  $A = \begin{bmatrix} 4 & -1 & 0 \\ 2 & 1 & 0 \\ 2 & -1 & 2 \end{bmatrix}$

$$\det(A - \lambda I) = \begin{vmatrix} 4-\lambda & -1 & 0 \\ 2 & 1-\lambda & 0 \\ 2 & -1 & 2-\lambda \end{vmatrix} = \dots = -(\lambda-2)^2(\lambda-3)$$

$$\lambda=2 \quad A-2I = \begin{bmatrix} 2 & -1 & 0 \\ 2 & -1 & 0 \\ 2 & -1 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -\frac{1}{2} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \begin{array}{l} x_1 - \frac{1}{2}x_2 = 0 \\ x_2, x_3 \text{ free} \end{array}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \frac{1}{2}x_2 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} \frac{1}{2} \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

A basis for the eigenspace of  $A$  corresponding to  $\lambda=2$  is  $\left\{ \begin{bmatrix} \frac{1}{2} \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$

$$\lambda=3 \quad A-3I = \begin{bmatrix} 1 & -1 & 0 \\ 2 & -2 & 0 \\ 2 & -1 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \quad \begin{array}{l} x_1 = x_3 \\ x_2 = x_3 \\ x_3 \text{ free} \end{array}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

A basis for the eigenspace of  $A$  corresponding to  $\lambda=3$  is  $\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$

### Theorem.

Let  $A$  be an  $n \times n$  matrix and let  $\vec{v}_1, \dots, \vec{v}_p$  be eigenvectors of  $A$  that correspond to *distinct* eigenvalues  $\lambda_1, \dots, \lambda_p$  respectively. Then  $\{\vec{v}_1, \dots, \vec{v}_p\}$  is a linearly independent set of vectors.

### Theorem. [Review: Diagonalizability]

Let  $A$  be an  $n \times n$  matrix.

$A$  is diagonalizable if and only if it has  $n$  linearly independent eigenvectors. (eigenbasis.)

In this case  $A = PDP^{-1}$  where the columns of  $P$  are eigenvectors of  $A$ ; the diagonal entries of  $D$  are the eigenvalues of  $A$  corresponding to the eigenvectors given by the columns of  $P$ .

**Example 3.** Diagonalizing Matrix  $A = \begin{bmatrix} 4 & -1 & 0 \\ 2 & 1 & 0 \\ 2 & -1 & 2 \end{bmatrix}$

$$P = \begin{bmatrix} \frac{1}{2} & 0 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \quad D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

**Proposition.** [Case of Distinct Eigenvalues]

If an  $n \times n$  matrix  $A$  has  $n$  **distinct** eigenvalues, then its corresponding eigenvectors are linearly independent and accordingly  $A$  is diagonalizable.

**Theorem.** [Case of Repeated Eigenvalues]

Let  $A$  be an  $n \times n$  matrix with distinct real eigenvalues  $\lambda_1, \dots, \lambda_p$  such that

$$f_A(\lambda) = \det(A - \lambda I) = (\lambda_1 - \lambda)^{k_1} (\lambda_2 - \lambda)^{k_2} \cdots (\lambda_p - \lambda)^{k_p}.$$

Suppose  $k_1 + k_2 + \cdots + k_p = n$ . Let  $E_k$  be the eigenspace of  $\lambda_k$ . Suppose  $B_k$  is a basis for  $E_k$ .

- $A$  is diagonalizable if and only if  $B = B_1 \cup \cdots \cup B_p$  is an eigen-basis for  $A$ .
- $A$  is diagonalizable if and only if

$$\dim E_1 + \cdots + \dim E_p = n.$$

This equality is satisfied if and only if  $\dim(E_i) = k_i$  for each  $i = 1, \dots, p$

**Example 4.** Diagonalizing Matrix  $A = \begin{bmatrix} 5 & 1 & 0 \\ 2 & 4 & 0 \\ 2 & 1 & 3 \end{bmatrix}$

$$D = \begin{bmatrix} 3 & & \\ & 3 & \\ & & 6 \end{bmatrix} \quad P = \begin{bmatrix} -1 & 0 & 1 \\ 2 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

**Theorem.** [Non Diagonalizing Result]

For any  $n > 1$  there exist examples of  $n \times n$  matrices that are not diagonalizable.

**Example 5.** For any  $n > 1$ , find examples of  $n \times n$  non-diagonalizable matrices.

$$\begin{bmatrix} k & 1 \\ 0 & k \end{bmatrix} \quad \begin{bmatrix} k & 1 & 0 \\ 0 & k & 1 \\ 0 & 0 & k \end{bmatrix} \quad \begin{bmatrix} k & 1 & & \\ & k & 1 & \\ & & k & 1 \\ & & & k \end{bmatrix} \quad \dots$$

**Example 6.** Diagonalizing the matrix  $A = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 2 & 1 \\ 2 & 1 & 1 \end{bmatrix}$ . We already know that 1, -1, 4 are eigenvalues of A.

For  $\lambda=1$

$$A - \lambda I = \begin{bmatrix} 0 & 1 & 2 \\ 1 & 1 & 1 \\ 2 & 1 & 0 \end{bmatrix} \rightarrow \dots \rightarrow \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix} \quad \vec{x} = x_3 \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

For  $\lambda=-1$

$$A - \lambda I = \begin{bmatrix} 2 & 1 & 2 \\ 1 & 3 & 1 \\ 2 & 1 & 2 \end{bmatrix} \rightarrow \dots \rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \vec{x} = x_3 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

For  $\lambda=4$

$$A - \lambda I = \begin{bmatrix} -3 & 1 & 2 \\ 1 & -2 & 1 \\ 2 & 1 & -3 \end{bmatrix} \rightarrow \dots \rightarrow \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \quad \vec{x} = x_3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$D = \begin{bmatrix} 1 & & \\ & -1 & \\ & & 4 \end{bmatrix} \quad P = \begin{bmatrix} 1 & -1 & 1 \\ -2 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

**Example 7.** Diagonalizing the matrix  $A = \begin{bmatrix} 2 & 1 & 2 \\ -1 & 4 & 2 \\ -1 & 1 & 5 \end{bmatrix}$ . We already know that 3 and 5 are eigenvalues of A.

$$D = \begin{bmatrix} 3 & & \\ & 3 & \\ & & 5 \end{bmatrix} \quad P = \begin{bmatrix} 1 & 2 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$